



# Radiofrequency Measurements

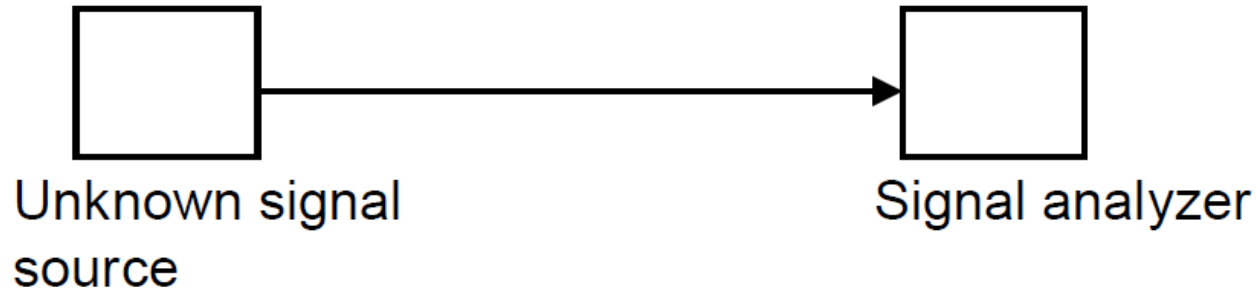
## Network Analyzer

The next slides material is taken from AGILENT “Network Analyzer Basics”:

- BTB\_Network\_2005.pdf
- SLDPRE\_BTBT\_2000Network.ppt
- 12-17-02-RF-network-analysis-Yates\_791-1mb.pdf

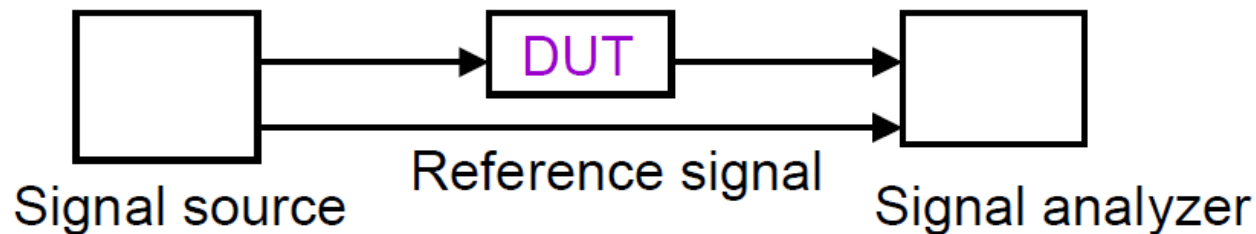
# Network VS Signal Analysis

Signal Analysis Characterizes an Unknown Signal



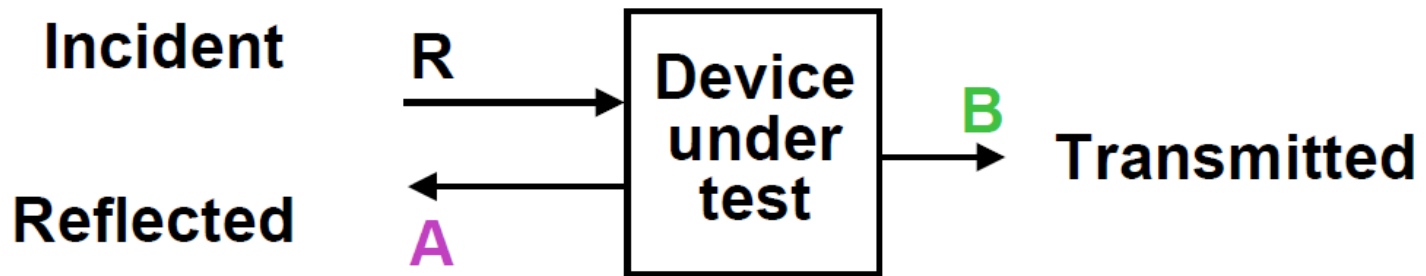
Network Analysis Characterizes an Unknown Circuit

(Device Under Test)



# How do we characterize devices?

1 Utilize a stimulus/response test system.



Network analyzer receivers R, A, and B

Reverse tests: Move stimulus to other port

# How do we characterize devices?

2 Measure the amplitude and phase ratios over the device's frequency.

**Forward and Reverse  
Transmitted and Reflected**

$$\begin{array}{l} \frac{\text{Transmitted}}{\text{Incident}} = \frac{\mathbf{B}}{\mathbf{R}} \\ \frac{\text{Reflected}}{\text{Incident}} = \frac{\mathbf{A}}{\mathbf{R}} \end{array} \left. \vphantom{\begin{array}{l} \frac{\text{Transmitted}}{\text{Incident}} = \frac{\mathbf{B}}{\mathbf{R}} \\ \frac{\text{Reflected}}{\text{Incident}} = \frac{\mathbf{A}}{\mathbf{R}} \end{array}} \right\} \text{vs frequency}$$

# How do we characterize devices?

**3** Calculate application parameters from the ratio data.

## Transmission Parameters

**Transmission coefficient,  
 $T$  and  $\tau$**

**Insertion gain and loss**

**S-parameters  $S_{21}$  and  $S_{12}$**

**Insertion phase**

**Group delay**

## Reflection Parameters

**Reflection coefficient,  
 $\Gamma$  and  $\rho$**

**Return loss**

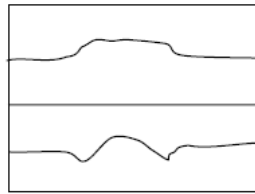
**S-parameters  $S_{11}$ ,  $S_{22}$**

**Impedance,  $Z$ ,  $R+jX$   
Admittance,  $A$ ,  $G+jB$**

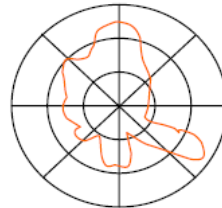
**Standing wave ratio, SWR**

# How do we characterize devices?

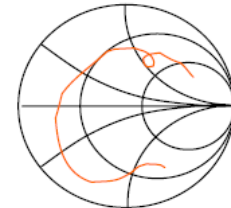
**4** Present the results as numerical, graphical, or data objects.



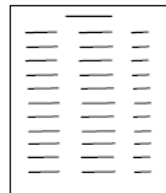
XY plot



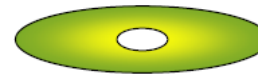
Polar plot



Smith chart

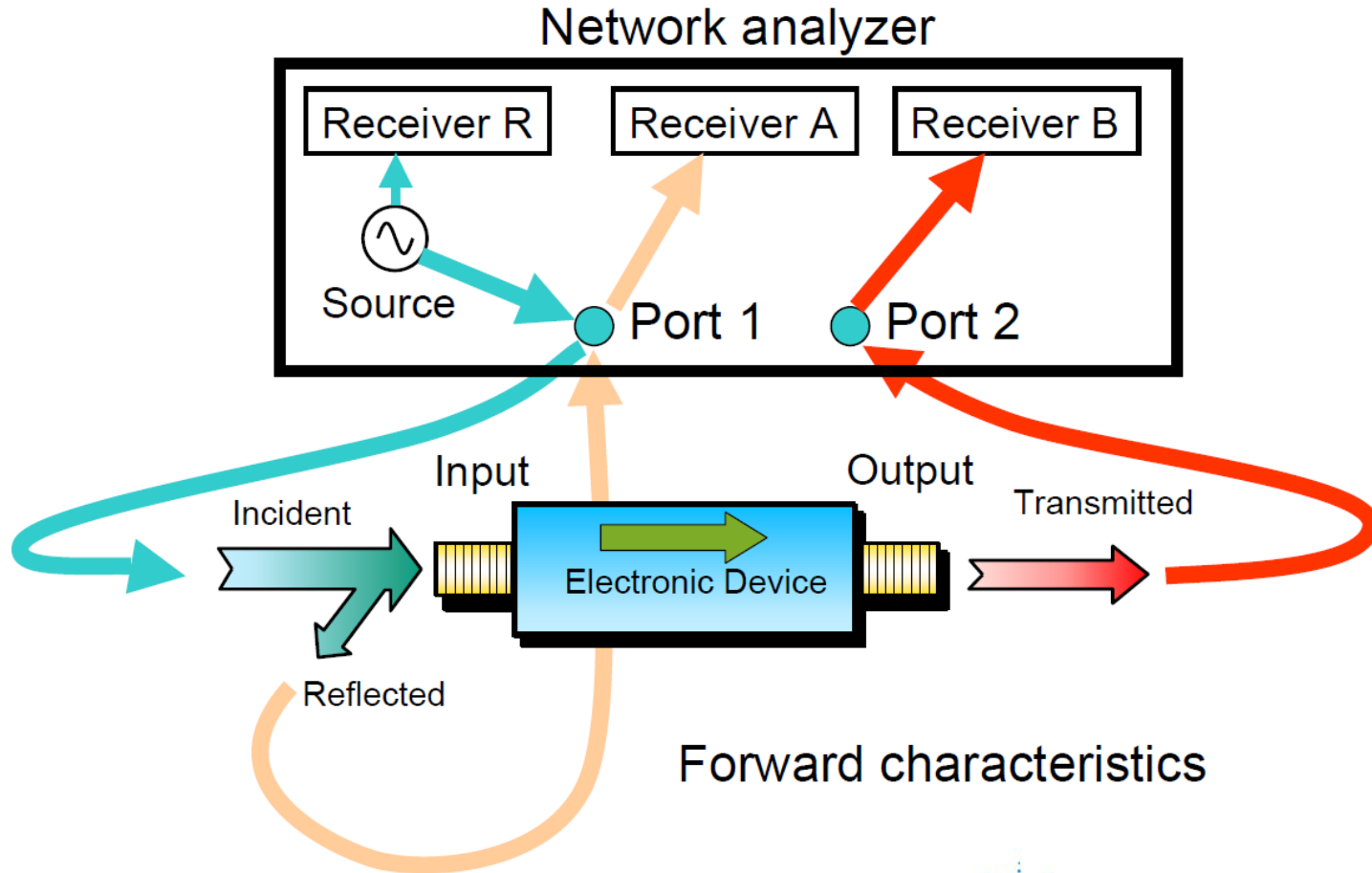


Printed table



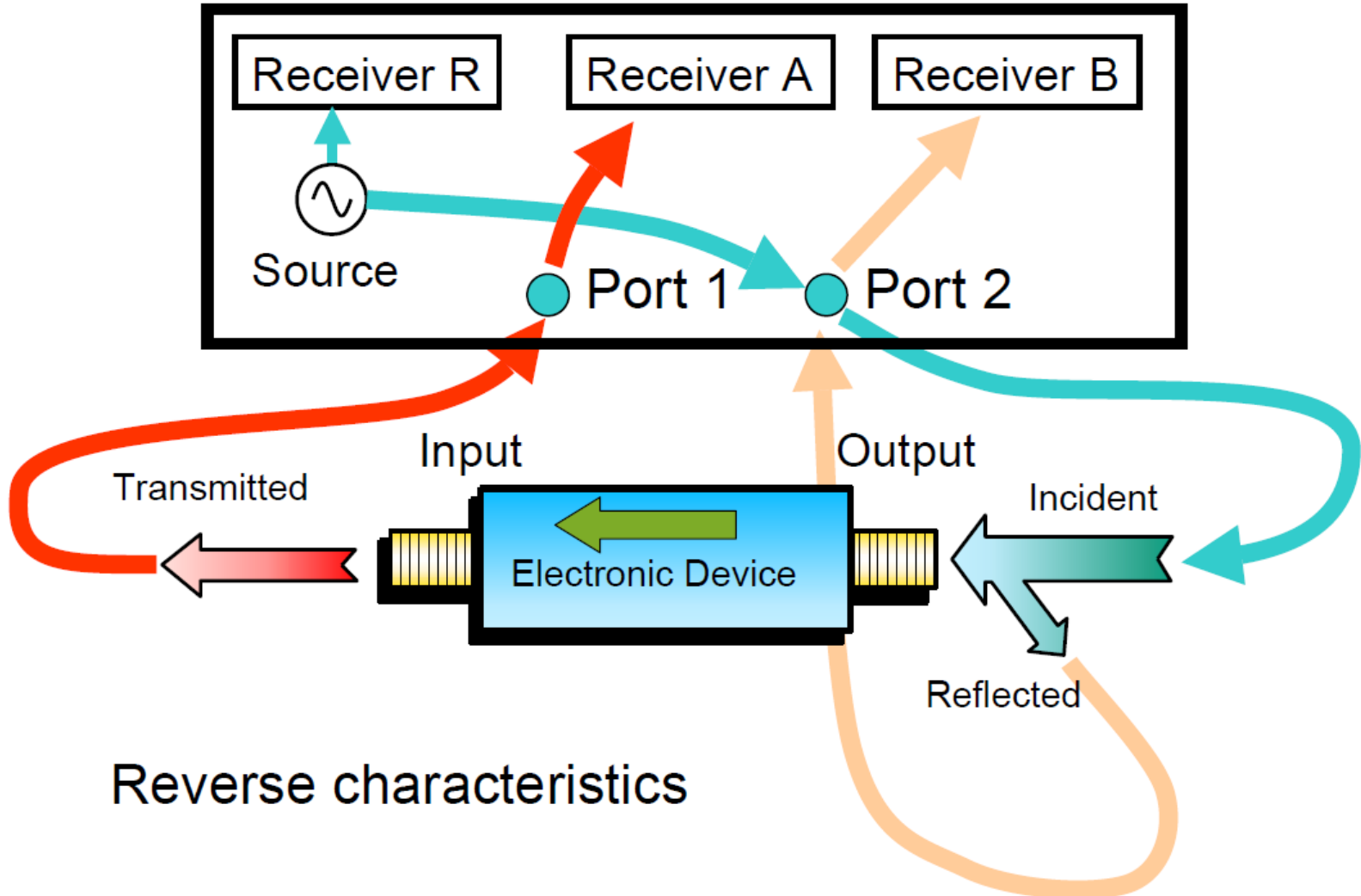
Data file

# Network Analyzer Operation



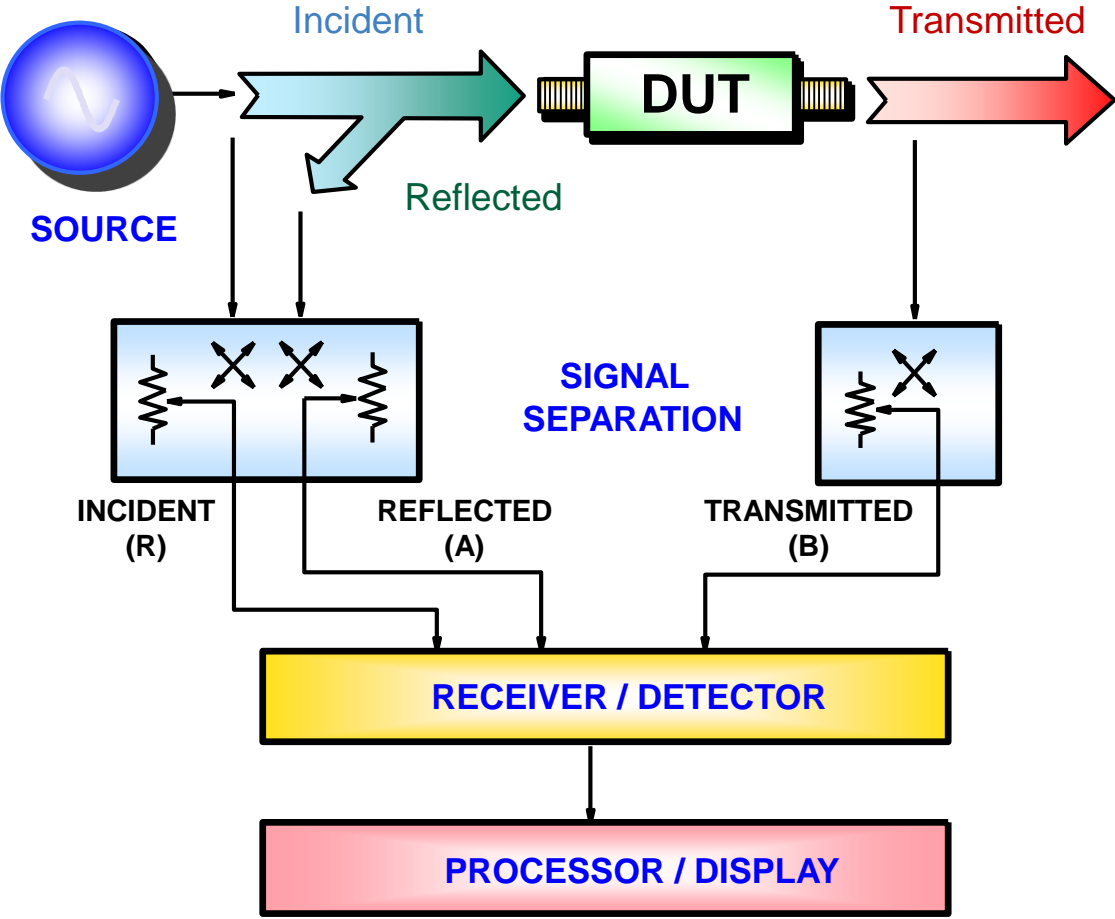


# Network Analyzer Operation



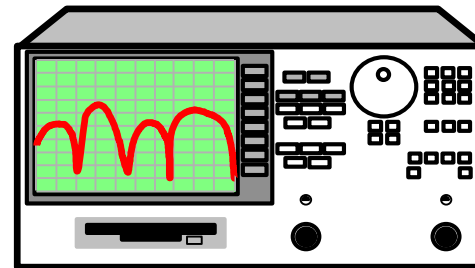
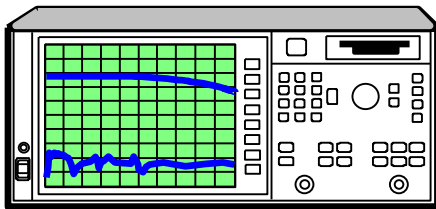
Reverse characteristics

# Generalized Network Analyzer Block Diagram

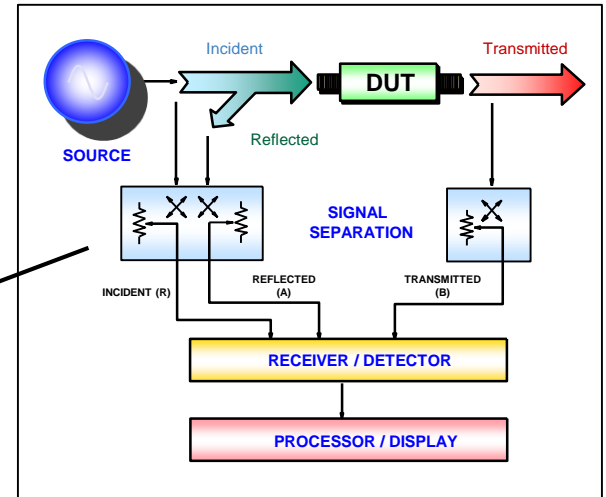


# Source

- Supplies stimulus for system
- Swept frequency or power
- Traditionally NAs used separate source
- Most Agilent analyzers sold today have **integrated, synthesized** sources

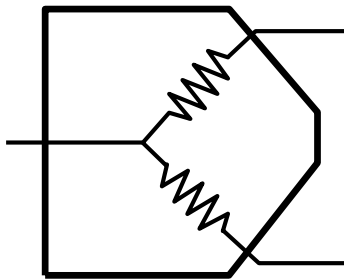


# Signal Separation

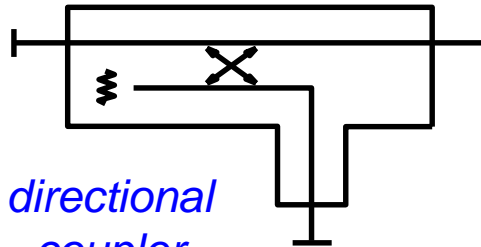


- measure incident signal for reference
- separate incident and reflected signals

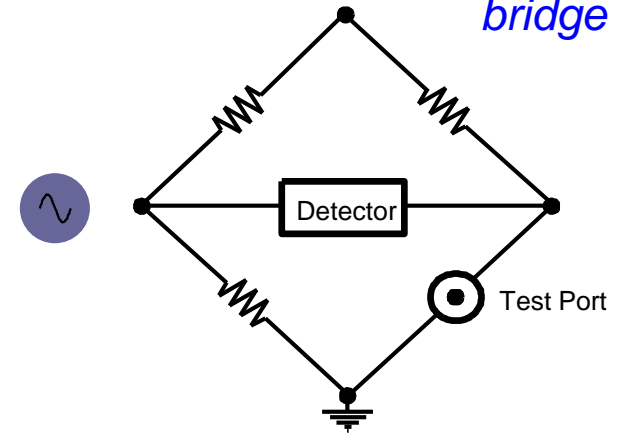
*splitter*



*directional coupler*

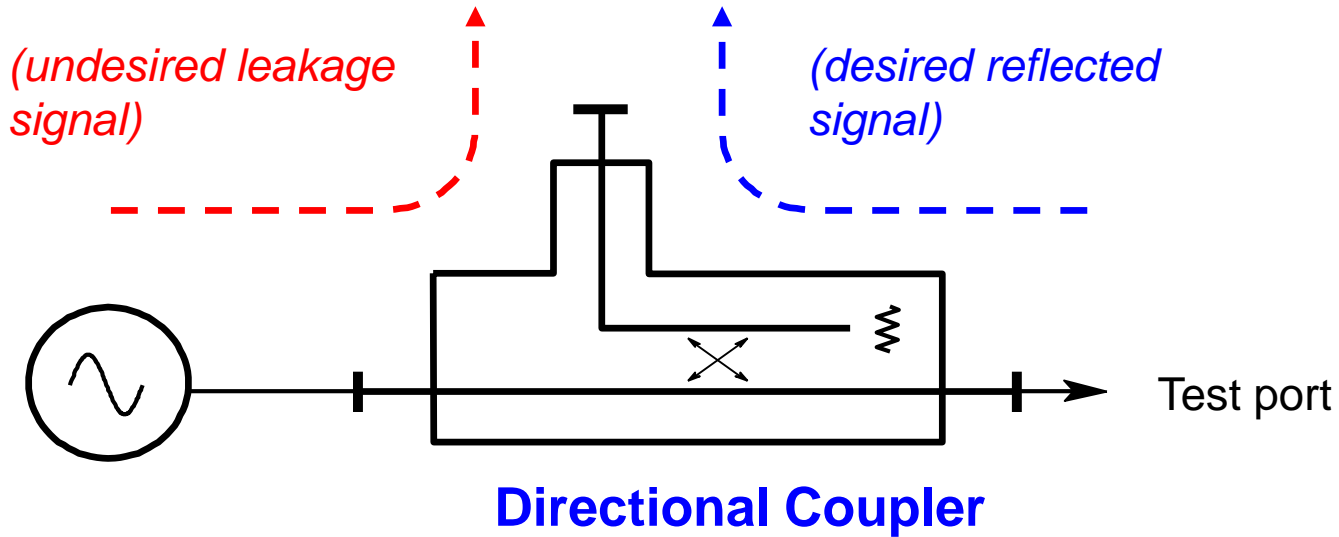


*bridge*



# Directivity

**Directivity** is a measure of how well a coupler can separate signals moving in opposite directions

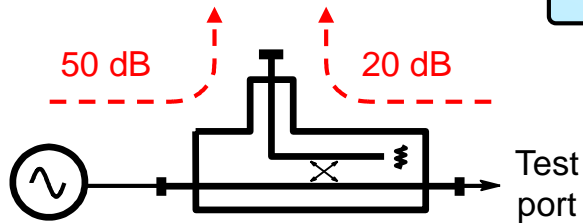


# Directional Coupler *Directivity*

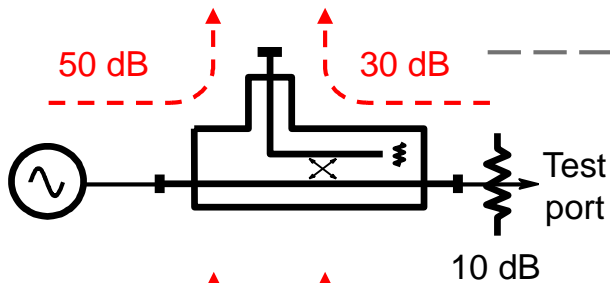
$$\text{Directivity} = \frac{\text{Coupling Factor}_{(\text{fwd})} \times \text{LOSS}_{(\text{through arm})}}{\text{Isolation}_{(\text{rev})}}$$

$$\text{Directivity (dB)} = \text{Isolation (dB)} - \text{Coupling Factor (dB)} - \text{Loss (dB)}$$

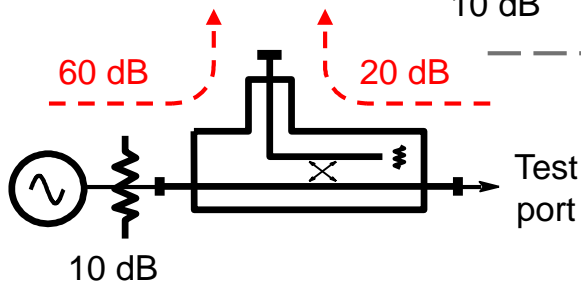
## *Examples:*



$$\text{Directivity} = 50 \text{ dB} - 20 \text{ dB} = 30 \text{ dB}$$

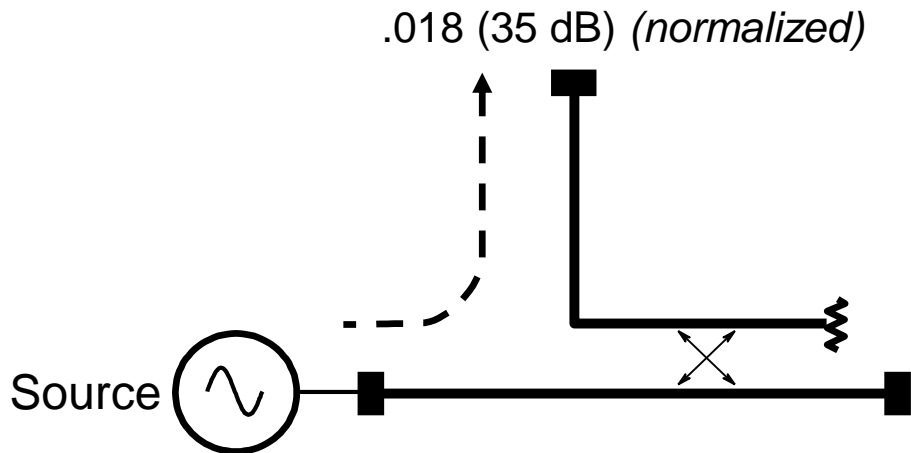
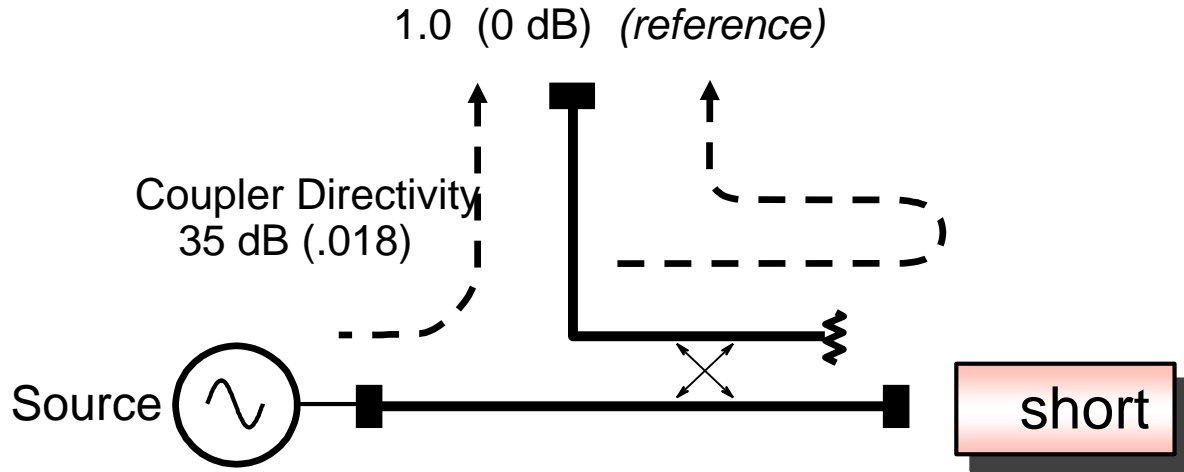


$$\text{Directivity} = 50 \text{ dB} - 30 \text{ dB} - 10 \text{ dB} = 10 \text{ dB}$$



$$\text{Directivity} = 60 \text{ dB} - 20 \text{ dB} - 10 \text{ dB} = 30 \text{ dB}$$

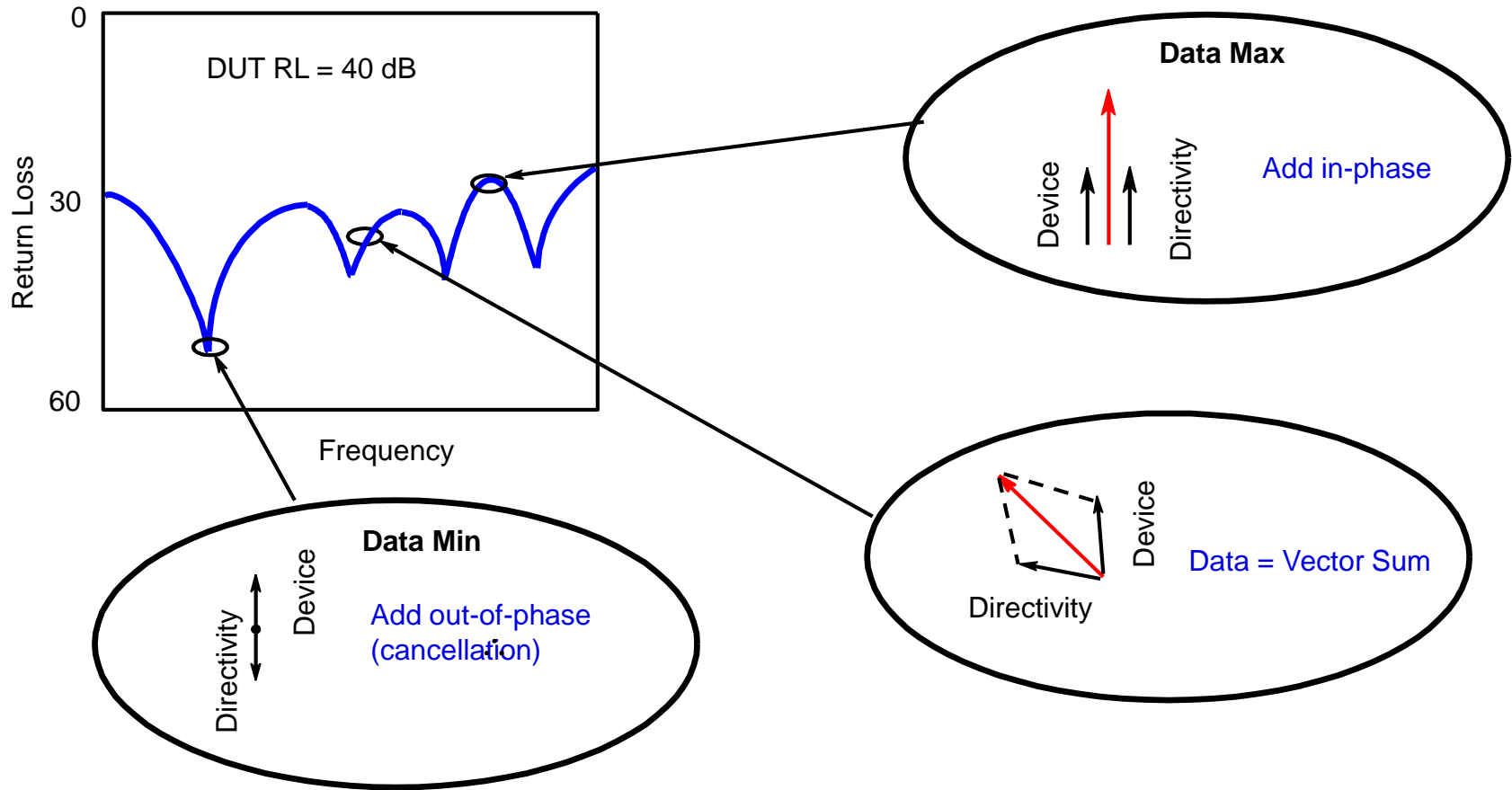
# One Method of Measuring Coupler Directivity



**Directivity = 35 dB - 0 dB  
= 35 dB**

Assume perfect load  
(no reflection)

# Interaction of Directivity with the DUT (Without Error Correction)



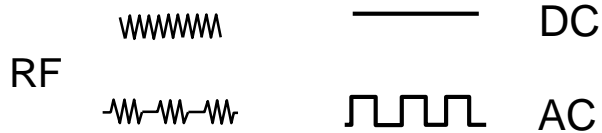


# Detector Types

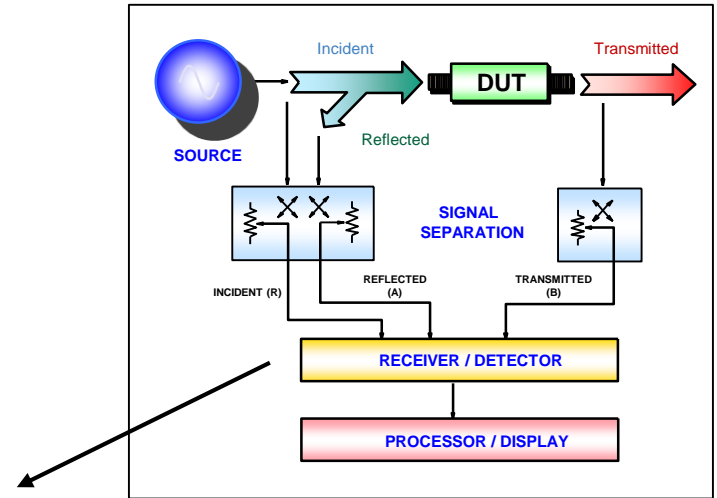
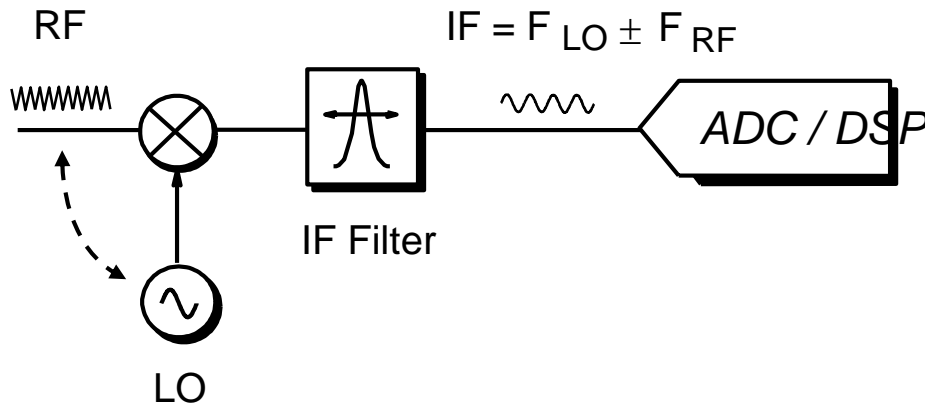
## Diode



Scalar **broadband**  
(no phase information)

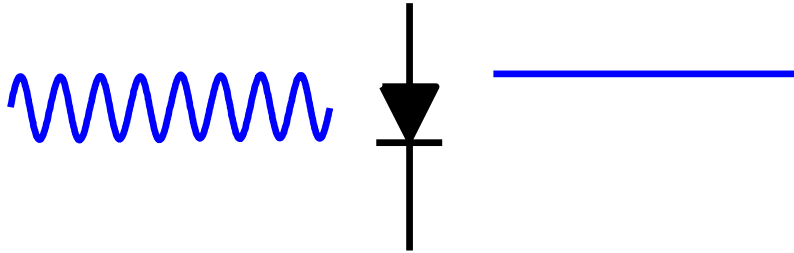


## Tuned Receiver

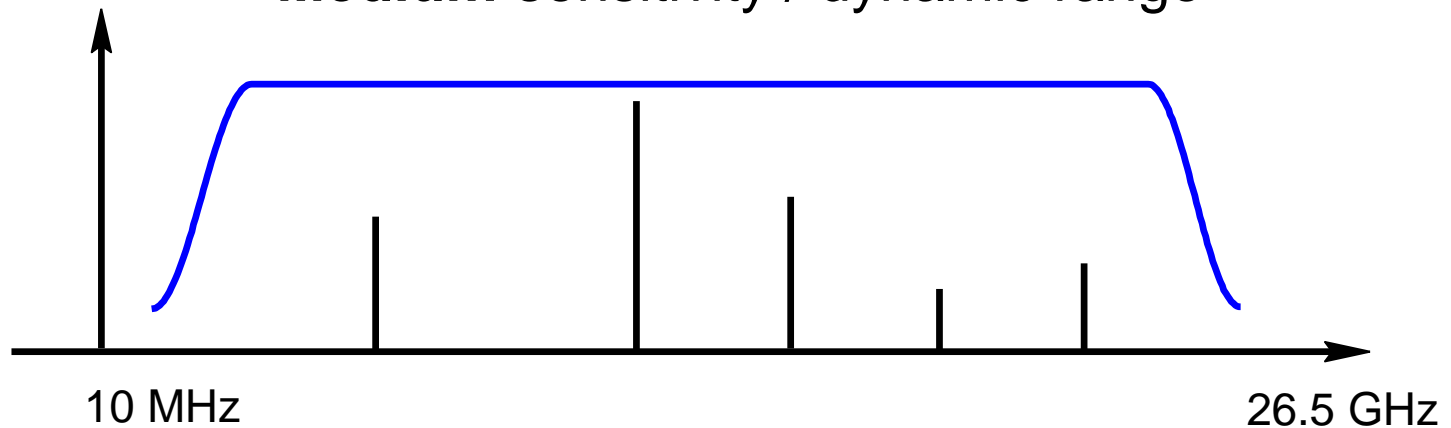


**Vector**  
(magnitude and phase)

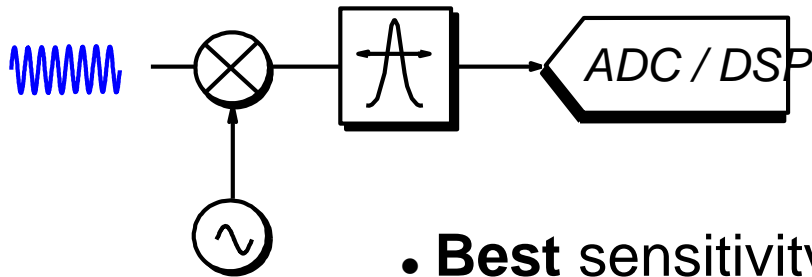
# Broadband Diode Detection



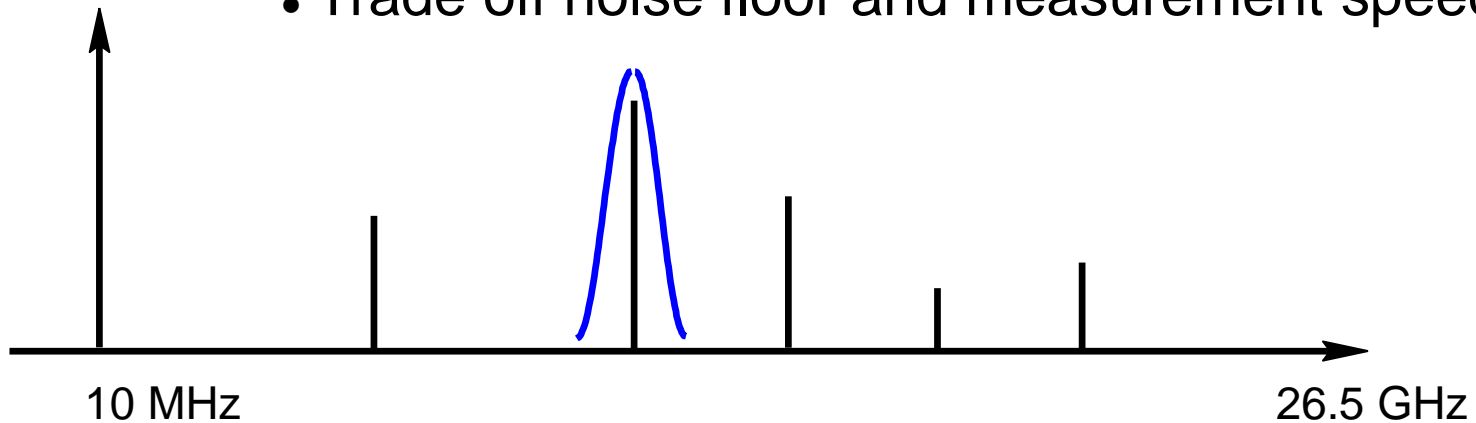
- Easy to make **broadband**
- **Inexpensive** compared to tuned receiver
- Good for measuring frequency-translating devices
- Improve dynamic range by increasing power
- **Medium** sensitivity / dynamic range



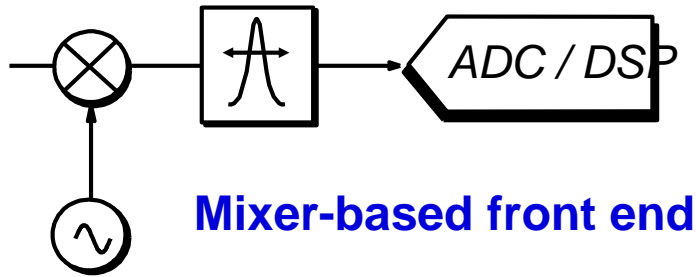
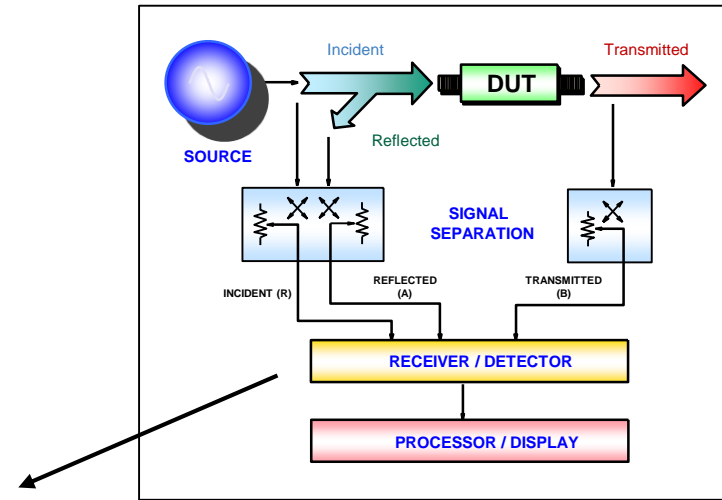
# Narrowband Detection - Tuned Receiver



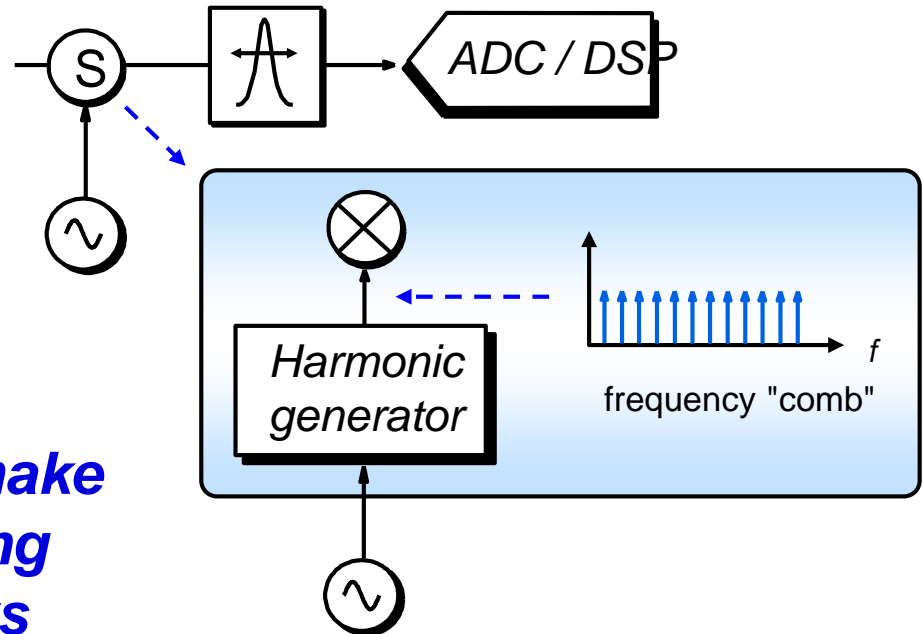
- **Best** sensitivity / dynamic range
- Provides harmonic / spurious signal **rejection**
- Improve dynamic range by increasing **power**, decreasing IF **bandwidth**, or **averaging**
- Trade off noise floor and measurement speed



# NA Hardware: Front Ends, Mixers Versus Samplers



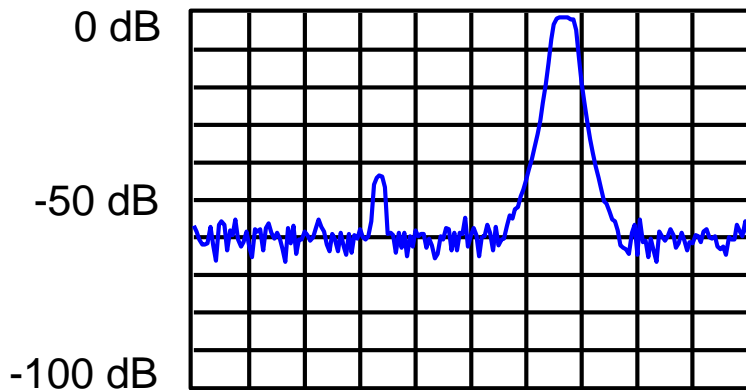
## Sampler-based front end



***It is cheaper and easier to make broadband front ends using samplers instead of mixers***

# Comparison of Receiver Techniques

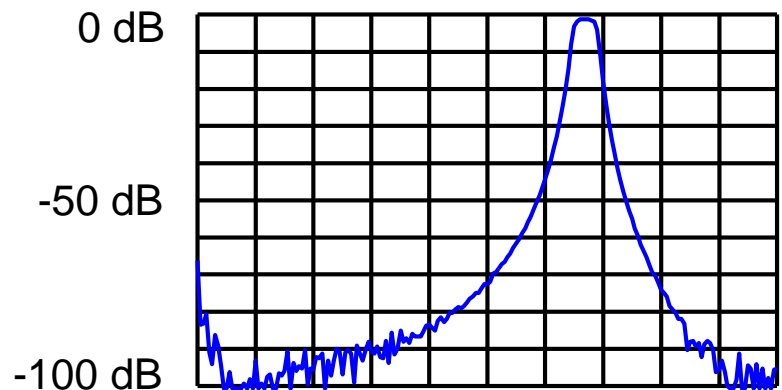
## ***Broadband (diode) detection***



-60 dBm Sensitivity

- higher noise floor
- false responses

## ***Narrowband (tuned-receiver) detection***



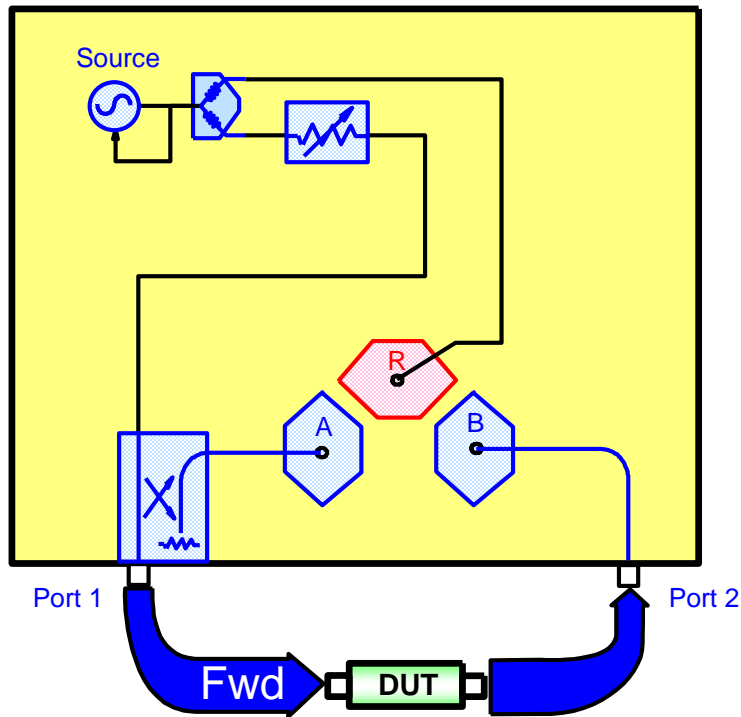
< -100 dBm Sensitivity

- high dynamic range
- harmonic immunity

***Dynamic range = maximum receiver power - receiver noise floor***

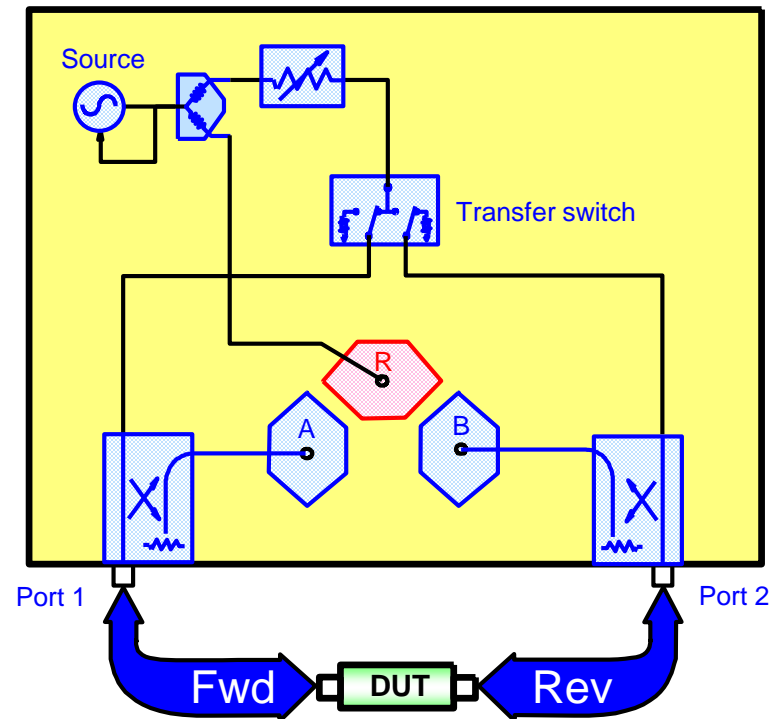
# T/R Versus S-Parameter Test Sets

## Transmission/Reflection Test Set



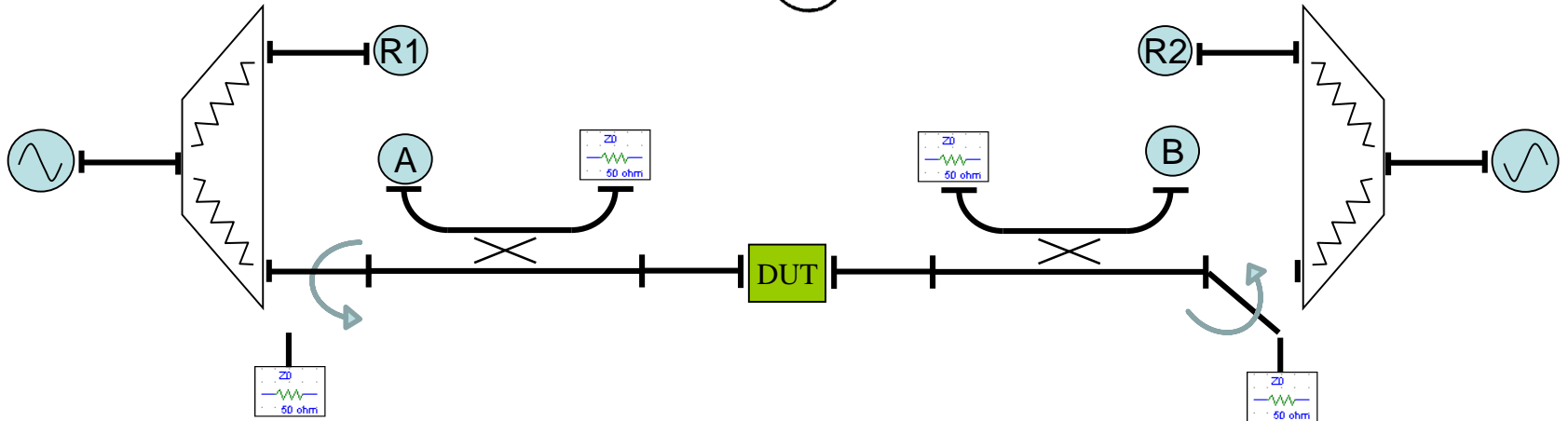
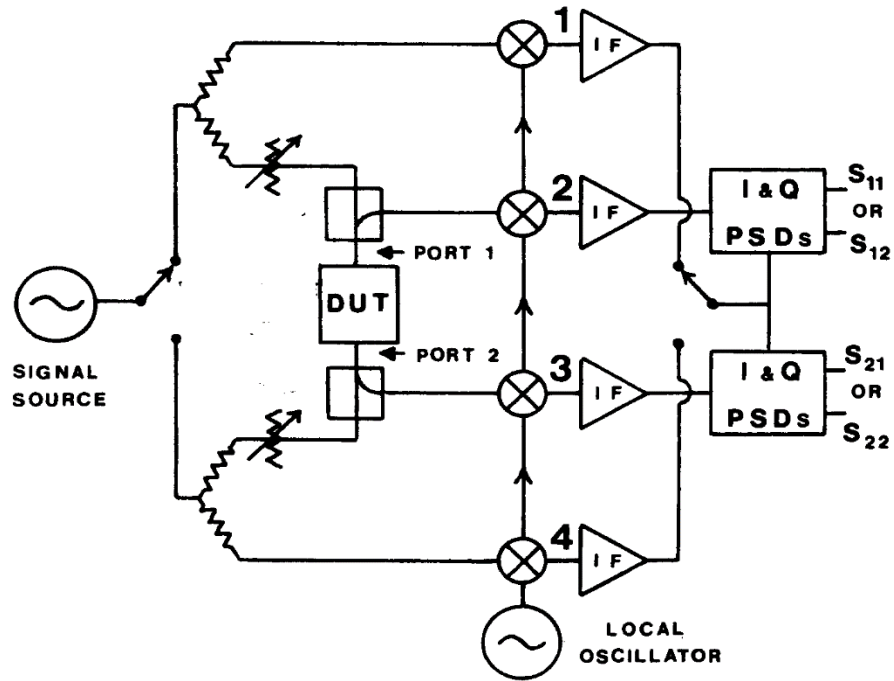
- RF always comes out port 1
- port 2 is always receiver
- **response, one-port** cal available

## S-Parameter Test Set

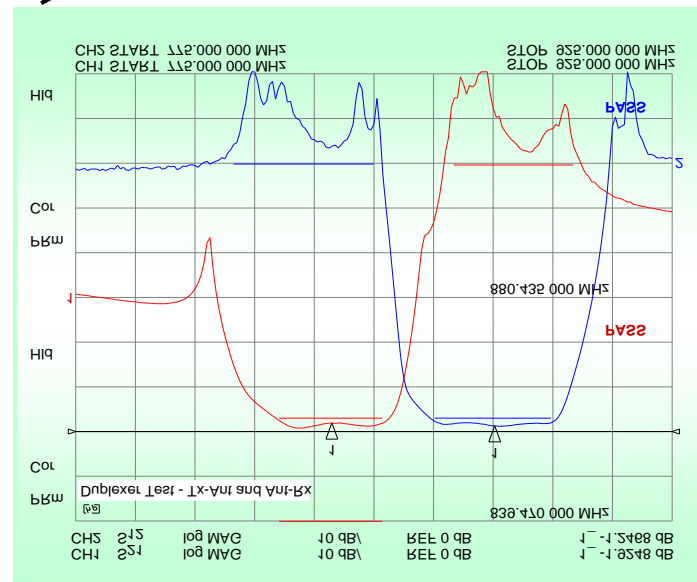
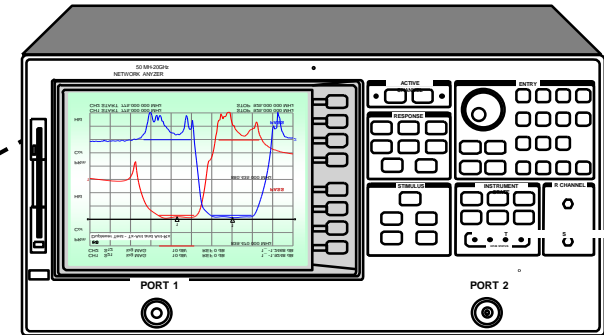
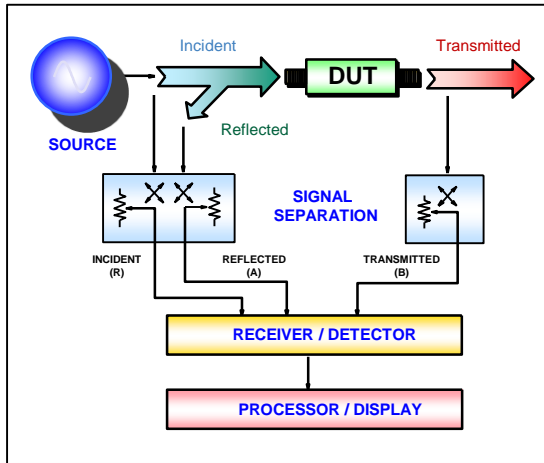


- RF comes out port 1 or port 2
- forward and reverse measurements
- **two-port** calibration possible

# Example of realization schemes



# Processor / Display



- markers
- limit lines
- pass/fail indicators
- linear/log formats
- grid/polar/Smith charts



# Measurement Error Modeling



## *Systematic errors*

- due to **imperfections** in the analyzer and test setup
- assumed to be **time invariant** (predictable)



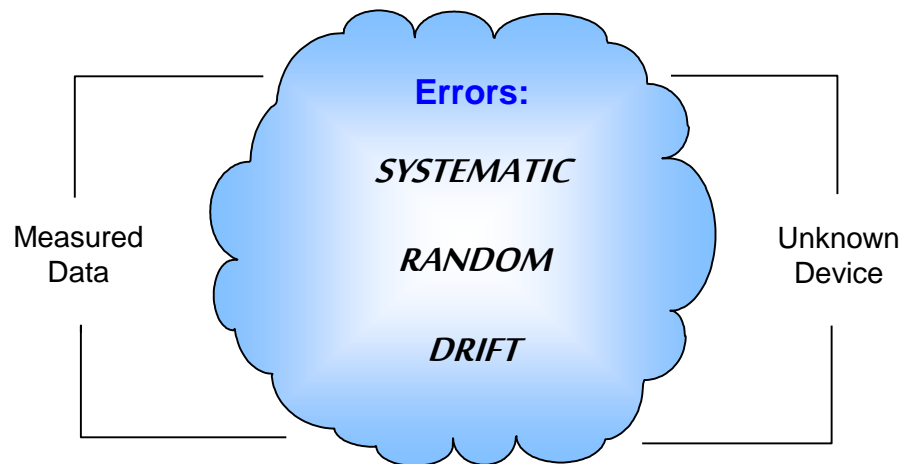
## *Random errors*

- **vary** with time in random fashion (unpredictable)
- main contributors: instrument **noise**, switch and connector **repeatability**

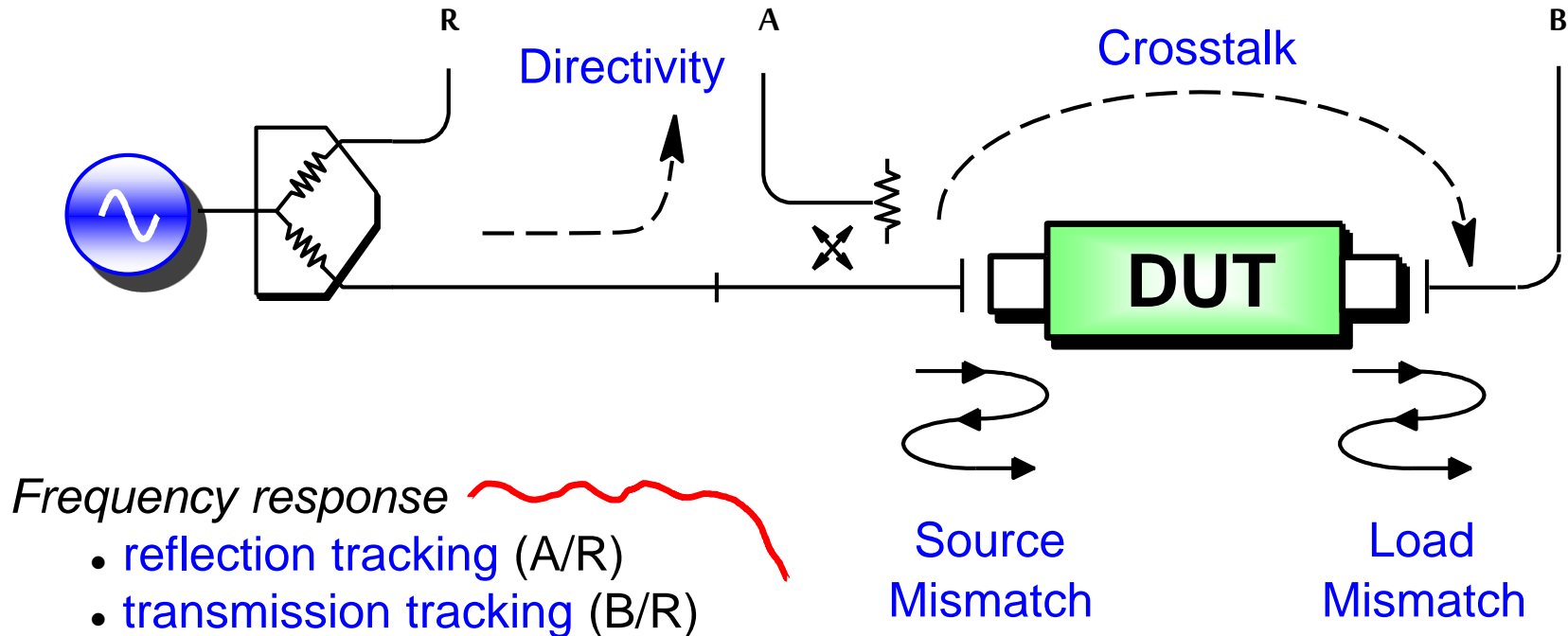


## *Drift errors*

- due to system performance changing **after** a calibration has been done
- primarily caused by **temperature variation**



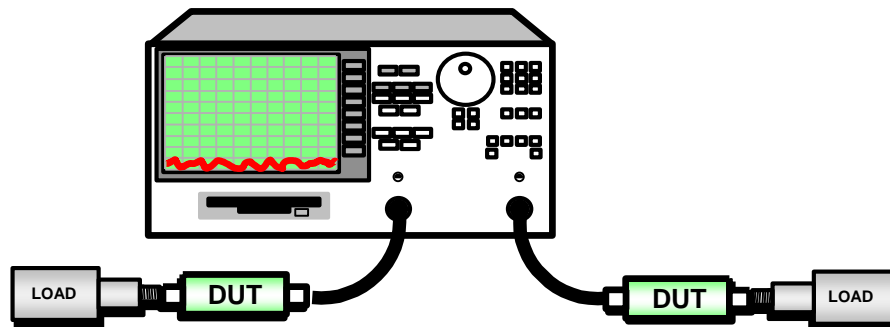
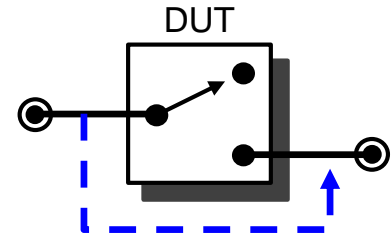
# Systematic Measurement Errors



***Six forward and six reverse error terms yields 12 error terms for two-port devices***

# Crosstalk: Signal Leakage Between Test Ports During Transmission

- Can be a problem with:
  - high-isolation devices (e.g., switch in open position)
  - high-dynamic range devices (some filter stopbands)
- Isolation calibration
  - adds noise to error model (measuring near noise floor of system)
  - only perform if really needed (use averaging if necessary)
  - if crosstalk is **independent** of DUT match, use two terminations
  - if **dependent** on DUT match, use DUT with termination on output



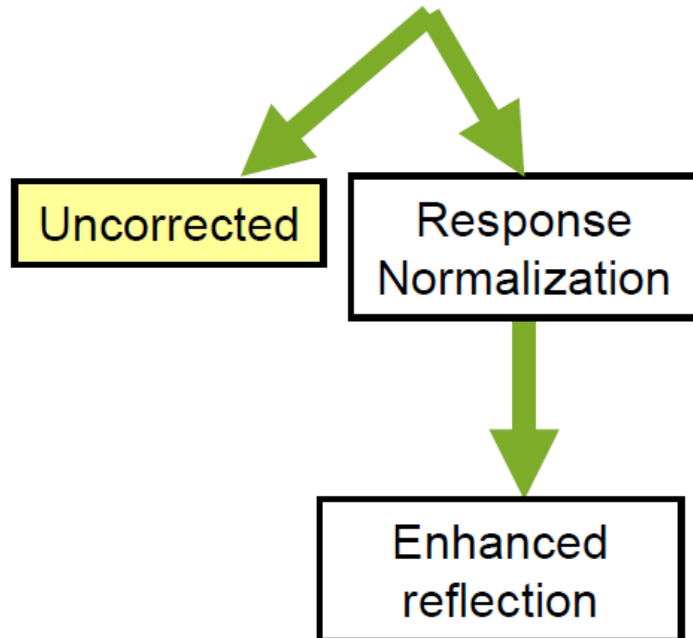
# Systematic Measurement Errors



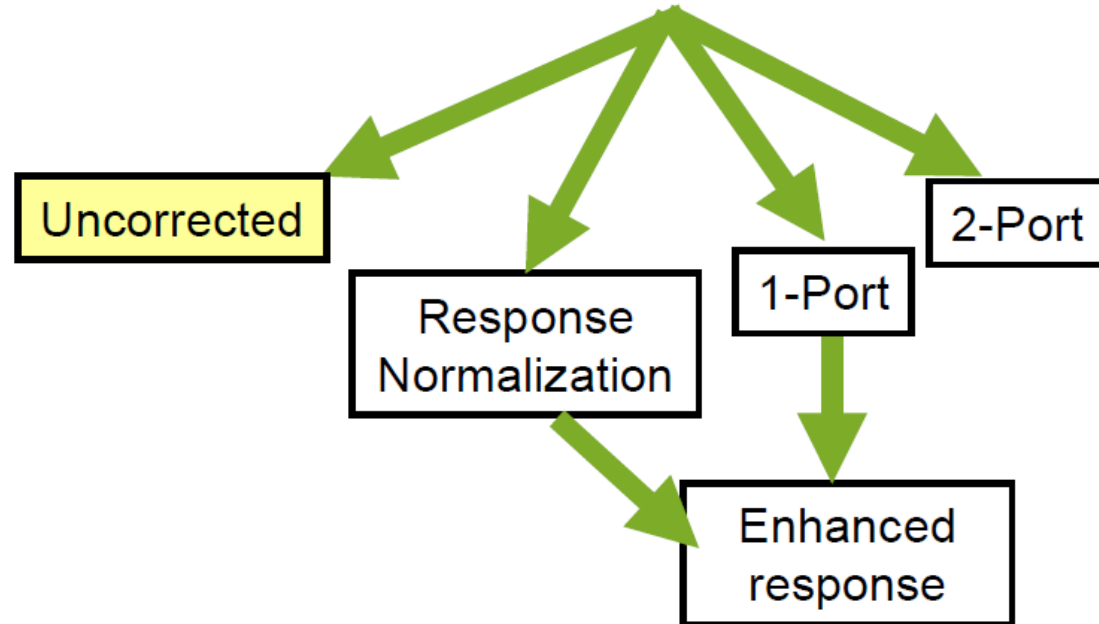
Complete characterization of a two port device requires ***forward and reverse*** measurements, for a total of **12 error terms**.

# Error Correction

## Scalar Network Analyzer



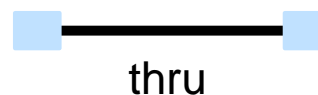
## Vector Network Analyzer



# Types of Error Correction

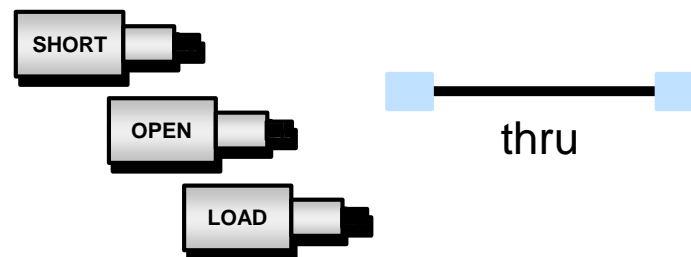
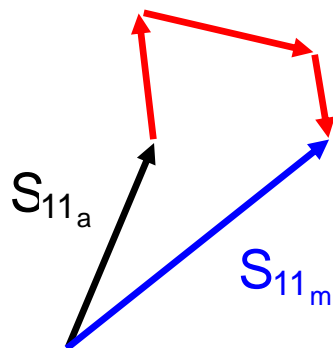
- **response (normalization)**

- simple to perform
- only corrects for tracking errors
- stores reference trace in memory, then does data divided by memory



- **vector**

- requires more standards
- requires an analyzer that can measure phase
- accounts for all major sources of systematic error



# What is Vector-Error Correction?

- Process of characterizing systematic error terms
  - measure **known standards**
  - remove effects from subsequent measurements
- **1-port calibration** (reflection measurements)
  - only 3 systematic error terms measured
  - directivity, source match, and reflection tracking
- **Full 2-port calibration** (reflection and transmission measurements)
  - 12 systematic error terms measured
  - usually requires 12 measurements on four known standards (SOLT)
- Standards defined in cal kit definition file
  - network analyzer contains standard cal kit definitions
  - **CAL KIT DEFINITION MUST MATCH ACTUAL CAL KIT USED!**
  - User-built standards must be characterized and entered into user cal-kit



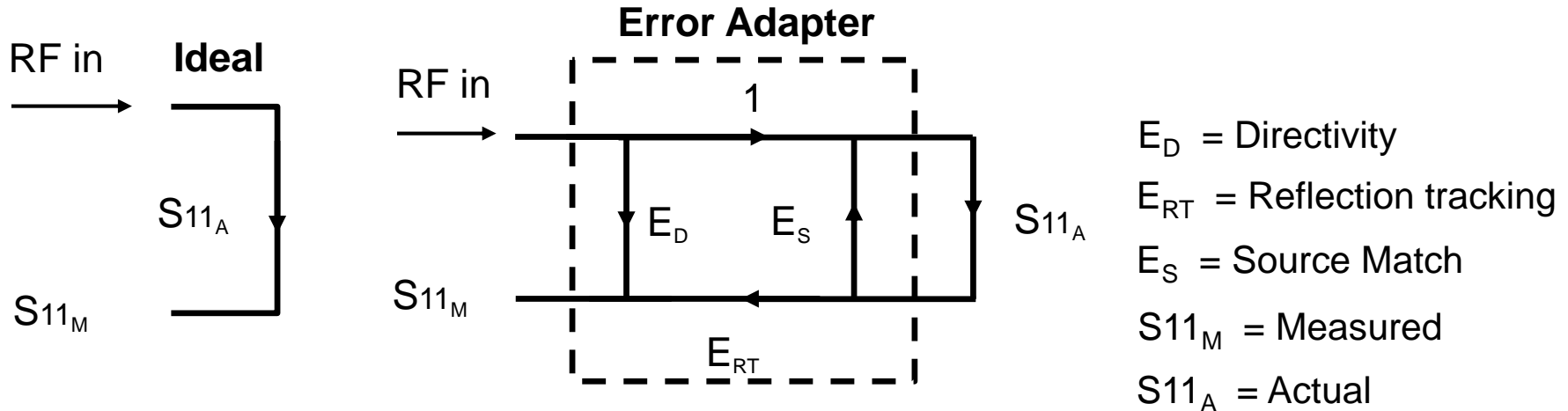
# Error Correction Procedure

1. Measure the calibration (impedance) standards.
2. Compute and store the error-correction terms.
3. Measure the DUT and apply the correction data.

Calibration standards are devices whose characteristics are **precisely** known.



# Reflection: One-Port Model

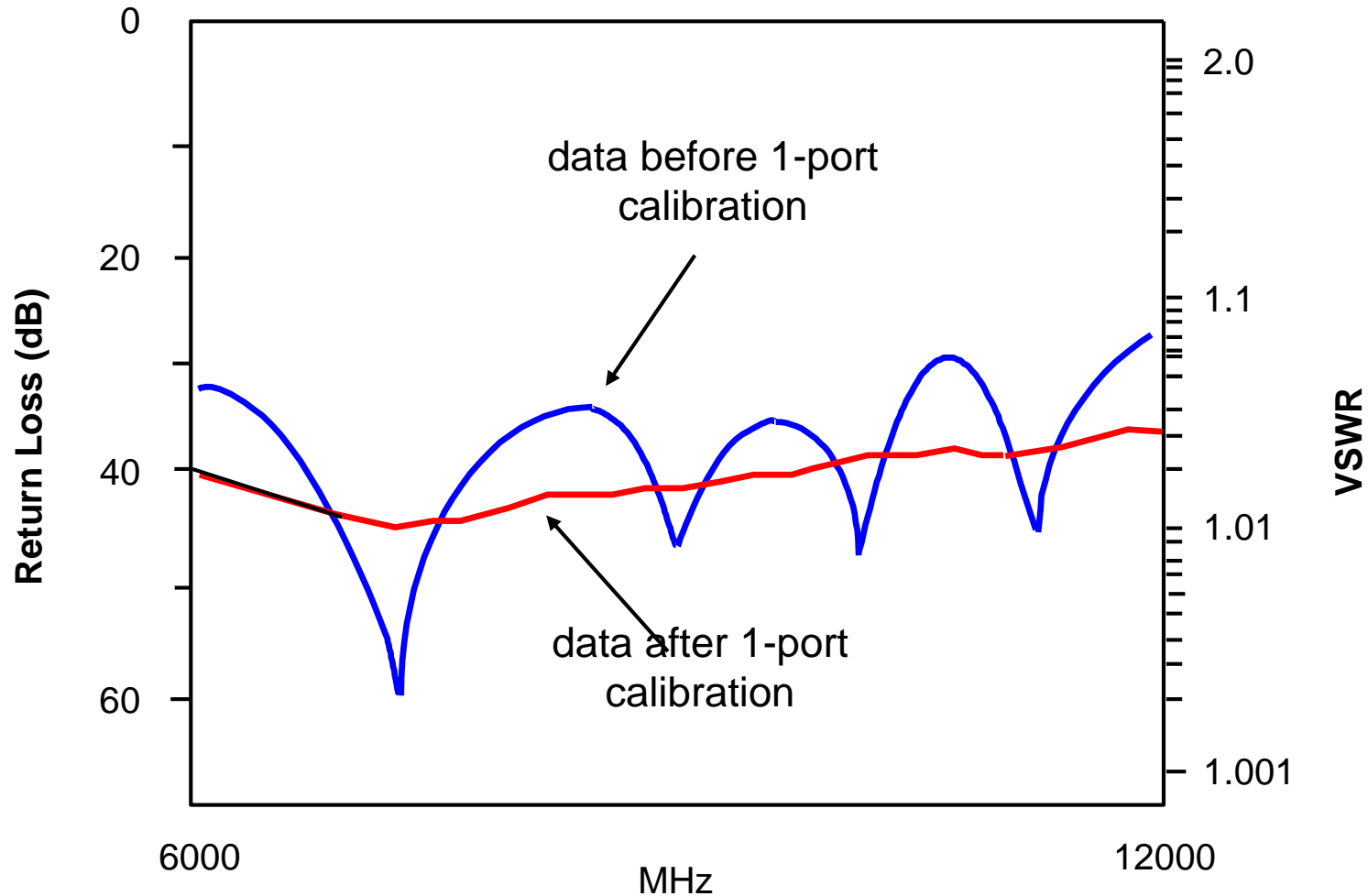


**To solve for error terms,  
we measure 3 standards  
to generate 3 equations  
and 3 unknowns**

$$S_{11M} = E_D + \frac{S_{11A}}{1 - E_S S_{11A}}$$

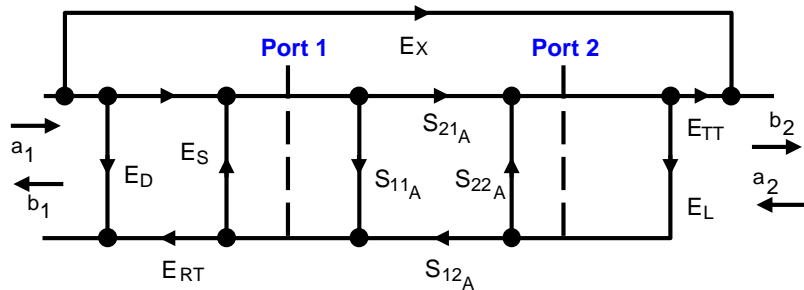
- Assumes good termination at port two if testing two-port devices
- If using port 2 of NA *and* DUT reverse isolation is low (e.g., filter passband):
  - assumption of good termination is not valid
  - two-port error correction yields better results

# Before and After One-Port Calibration

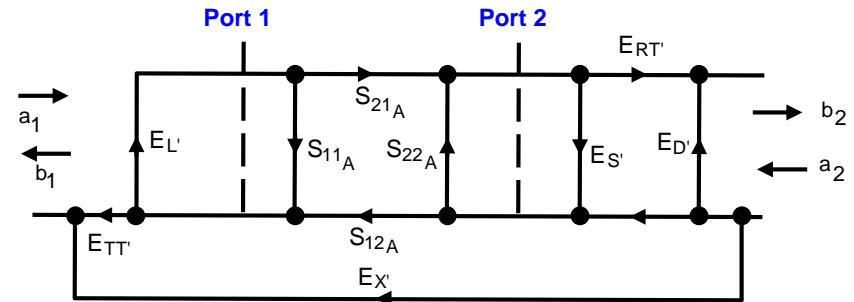


# Two-Port Error Correction

Forward model



Reverse model



- |                                     |                                       |
|-------------------------------------|---------------------------------------|
| $E_D$ = fwd directivity             | $E_L$ = fwd load match                |
| $E_S$ = fwd source match            | $E_{TT}$ = fwd transmission tracking  |
| $E_{RT}$ = fwd reflection tracking  | $E_X$ = fwd isolation                 |
| $E_{D'}$ = rev directivity          | $E_{L'}$ = rev load match             |
| $E_{S'}$ = rev source match         | $E_{TT'}$ = rev transmission tracking |
| $E_{RT'}$ = rev reflection tracking | $E_{X'}$ = rev isolation              |

- Each actual S-parameter is a function of all four measured S-parameters
- Analyzer must make forward *and* reverse sweep to update any one S-parameter
- Luckily, you don't need to know these equations to **use** network analyzers!!!

$$S_{11a} = \frac{\left(\frac{S_{11m} - E_D}{E_{RT}}\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} E_{S'}\right) - E_L \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}{\left(1 + \frac{S_{11m} - E_D}{E_{RT}} E_S\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} E_{S'}\right) - E_{L'} E_L \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}$$

$$S_{21a} = \frac{\left(\frac{S_{21m} - E_X}{E_{TT}}\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} (E_{S'} - E_L)\right)}{\left(1 + \frac{S_{11m} - E_D}{E_{RT}} E_S\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} E_{S'}\right) - E_{L'} E_L \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}$$

$$S_{12a} = \frac{\left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)\left(1 + \frac{S_{11m} - E_D}{E_{RT}} (E_S - E_{L'})\right)}{\left(1 + \frac{S_{11m} - E_D}{E_{RT}} E_S\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} E_{S'}\right) - E_{L'} E_L \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}$$

$$S_{22a} = \frac{\left(\frac{S_{22m} - E_{D'}}{E_{RT'}}\right)\left(1 + \frac{S_{11m} - E_D}{E_{RT}} E_S\right) - E_{L'} \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}{\left(1 + \frac{S_{11m} - E_D}{E_{RT}} E_S\right)\left(1 + \frac{S_{22m} - E_{D'}}{E_{RT'}} E_{S'}\right) - E_{L'} E_L \left(\frac{S_{21m} - E_X}{E_{TT}}\right) \left(\frac{S_{12m} - E_{X'}}{E_{TT'}}\right)}$$

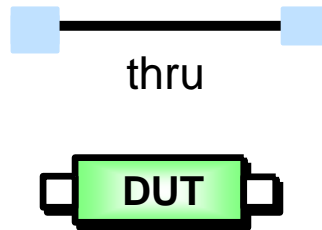
# Errors and Calibration Standards

## UNCORRECTED FULL 2-PORT



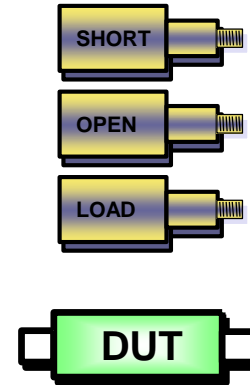
- Convenient
- Generally not accurate
- No errors removed

## RESPONSE

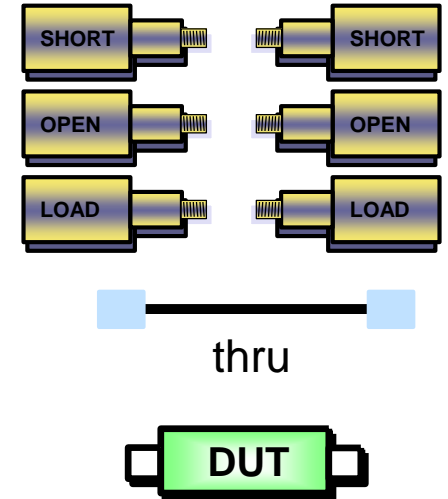


- Easy to perform
- Use when highest accuracy is not required
- Removes frequency response error

## 1-PORT



- For reflection measurements
- Need good termination for high accuracy with two-port devices
- Removes these errors:
  - Directivity
  - Source match
  - Reflection tracking

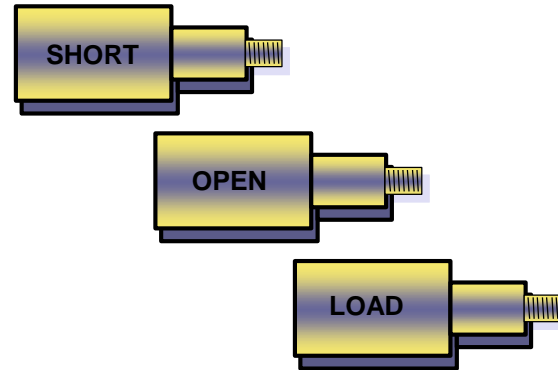


- Highest accuracy
- Removes these errors:
  - Directivity
  - Source, load match
  - Reflection tracking
  - Transmission tracking
  - Crosstalk

## ENHANCED-RESPONSE




- Combines response and 1-port
- Corrects source match for transmission measurements

# Calibration Summary



Reflection	Test Set (cal type)	
	T/R (one-port)	S-parameter (two-port)
• Reflection tracking	✓	✓
• Directivity	✓	✓
• Source match	✓	
• Load match	✗	

Transmission	Test Set (cal type)	
	T/R (response, isolation)	S-parameter (two-port)
• Transmission Tracking	✓	✓
• Crosstalk	✓	✓
• Source match (✓*)	✗	✓
• Load match	✗	✓

 **error can be corrected**  
 **error cannot be corrected**  
 \* *enhanced response cal corrects for source match during transmission measurements*

# Response versus Two-Port Calibration

## Measuring filter insertion loss



# ECal: Electronic Calibration

- Variety of modules cover 30 kHz to 67 GHz
- Eight connector types available (50  $\Omega$  and 75  $\Omega$ )
- Single-connection
  - reduces calibration time
  - makes calibrations easy to perform
  - minimizes wear on cables and standards
  - eliminates operator errors
- Highly repeatable temperature-compensated terminations provide excellent accuracy

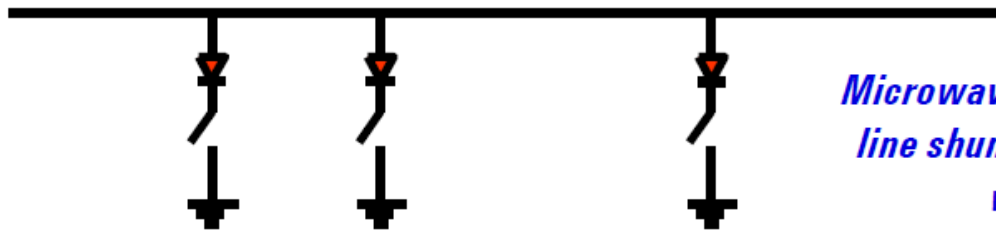
N4431A



85092C



N4691A



*Microwave modules use a transmission line shunted by PIN-diode switches in various combinations*

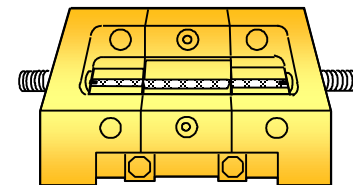
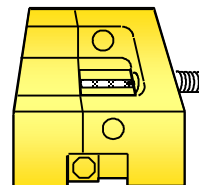
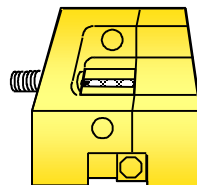
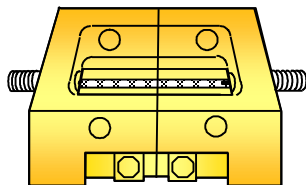
# Thru-Reflect-Line (TRL) Calibration

We know about Short-Open-Load-Thru (SOLT) calibration...

What is TRL?

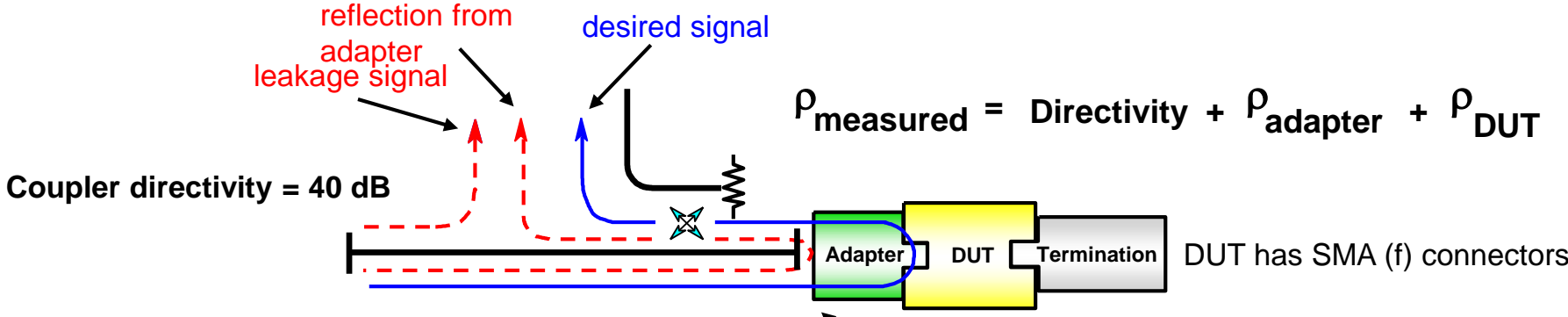
- A two-port calibration technique
- Good for noncoaxial environments (waveguide, fixtures, wafer probing)
- Uses the same 12-term error model as the more common SOLT cal
- Uses practical calibration standards that are easily fabricated and characterized
- Two variations: TRL (requires 4 receivers) and TRL\* (only three receivers needed)
- Other variations: Line-Reflect-Match (LRM),
- Thru-Reflect-Match (TRM), plus many others

*TRL was developed for **non-coaxial** **microwave** measurements*



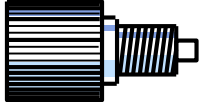
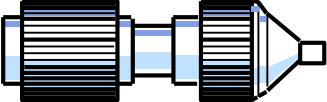
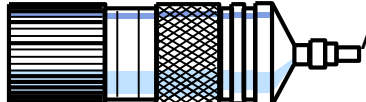


# Adapter Considerations



Worst-case System Directivity

Adapting from APC-7 to SMA (m)

- 28 dB  APC-7 to SMA (m)  
SWR:1.06
- 17 dB  APC-7 to N (f) + N (m) to SMA (m)  
SWR:1.05      SWR:1.25
- 14 dB  APC-7 to N (m) + N (f) to SMA (f) + SMA (m) to (m)  
SWR:1.05      SWR:1.25      SWR:1.15

# Calibrating Non-Insertable Devices

## When doing a through cal, normally test ports mate directly

- cables can be connected directly without an adapter
- result is a zero-length through



## What is an insertable device?

- has same type of connector, but different sex on each port
- has same type of sexless connector on each port (e.g. APC-7)

## What is a non-insertable device?

- one that cannot be inserted in place of a zero-length through
- has same connectors on each port (type and sex)
- has different type of connector on each port  
(e.g., waveguide on one port, coaxial on the other)



## What calibration choices do I have for non-insertable devices?

- use an *uncharacterized* through adapter
- use a *characterized* through adapter (modify cal-kit definition)
- swap equal adapters
- adapter removal